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**B.E.(Electronics Engineering) (Part - IV) (Semester - VII) (Old)**  
**Examination, November - 2016**  
**POWER ELECTRONICS AND DRIVES**  
**Sub. Code : 47947**

Day and Date :Thursday, 17-11-2016  
Time : 2.30 p.m. to 5.30 p.m.

Total Marks : 100

- Instructions :
- 1) All questions are compulsory.
  - 2) Figures to the right indicate full marks.
  - 3) Assume suitable data if necessary and clearly maintain in your answer.

**SECTION - I**

**Q1) Attempt any two [18]**

- a) Three phase full controlled converter is supplied from 360 volt 50 Hz supply. The load is purely resistive 10 ohm the average voltage is 50% of maximum possible output voltage determine Firing angle, Average, RMS and Peak SCR current.
- b) Explain with different operating modes operation of semiconverter at RL load. Derive expression for average and rms load voltage.
- c) Write short note on effect of source inductance on performance of 3-phase controlled converters, derive expression for average load voltage in overlapping time interval  $\mu$ .

**Q2) Attempt any two [16]**

- a) Draw circuit diagram of inverse cosine firing scheme and explain with waveforms.
- b) Draw block diagram of microcontroller based single phase fully controlled converter and explain with waveforms.
- c) What is need of isolation circuit? Explain the different types of isolation circuits.

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- Q3) Attempt any two [16]**
- a) What is need of cycloconverter? Explain operation of bridge type 1 phase to 1 phase cycloconverter.
  - b) Explain circulating current mode of operation of 1 phase to 1 phase cycloconverter.
  - c) Explain methods of harmonic reduction in cycloconverter output.

**SECTION - II**

- Q4) Attempt any two [18]**
- a) Explain operation of full bridge series inverter with circuit diagram and waveforms. List out limitations of it.
  - b) With neat circuit diagram and waveform explain operation of IGBT based three phase bridge inverter with 120° mode of conduction.
  - c) Explain operation of mac-murray half bridge inverter with different operating modes.

- Q5) Attempt any two [16]**
- a) With block diagram explain operation of PLL controlled closed loop operation of DC drive.
  - b) Explain multiquadrant operation of separately excited dc motor.
  - c) Explain with circuit diagram and torque speed characteristic operation of armature control of separately excited dc motor.

- Q6) Attempt any two [16]**
- a) Draw speed torque characteristic of induction motor and explain operating regions in details.
  - b) Explain operation of slip power recovery method of AC motor.
  - c) Why only voltage or only frequency control is not sufficient to control AC motor? With block diagram and torque speed characteristic explain operation of V/F control method.



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**B.E.(Electronics)(Part-I) (Semester -VII)(Revised)(New)  
Examination, November - 2016  
INFORMATION THEORY AND CODING TECHNIQUES  
Sub. Code :67526**

Day and Date :Tuesday, 15 -11 -2016  
Time :2.30 p.m. to 5.30 p.m.

Total Marks : 100

- Instructions :
- 1) All questions are compulsory.
  - 2) Figures to the right indicates full marks.
  - 3) Assume suitable data if necessary.

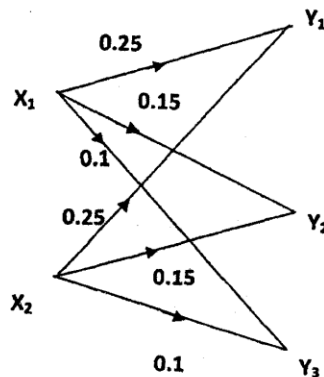
**SECTION-I**

Q1) Attempt any Three of the following: [18]

- a) A(5,1) linear block code generated by generator matrix  $G=[11111]$ .

Determine:

- i) Parity check matrix
  - ii) All code vectors
  - iii) Minimum distance & error correction capability
  - iv) If the received vector  $R=11011$  is received, find the corrected code word.
- b) Find the mutual information for the channel shown in figure(1).



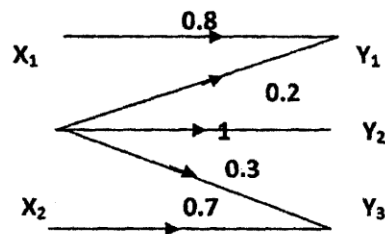
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- c) What do you mean by binary symmetric channel? Show that channel capacity in BSC is given by,  $C=1+P \log P+(1-P) \log (1-P)$
- d) What is Joint & Conditional entropy? Derive relation between joint and Conditional entropy.

**Q2) Attempt any Two of the following: [16]**

- a) Determine all the entropies and transferred information for the channel shown in figure(2), with  $P(y_1)=0.2$ ,  $P(y_2)=0.5$  and  $P(y_3)=0.3$



- b) i) Prove that maximum capacity of channel is given by,  
 $C_{\infty} = \lim_{B \rightarrow \infty} C = 1.44 [S / N_0]$
- ii) Design a single error correcting hamming code for a message length of 4.
- c) For a systematic linear Block code, the three parity check bits are,

$$C_4 = m_1 \oplus m_2 \oplus m_3$$

$$C_5 = m_2 \oplus m_3 \oplus m_4$$

$$C_6 = m_1 \oplus m_2 \oplus m_4$$

Determine:

- Generator Matrix(G) and parity check Matrix(H)
- All code vectors
- Error detecting and Correcting capability
- Prepare decoding table
- If the received code vector is (1011011), find transmitted message

Q3) Attempt any Two of the following: [16]

- a) Construct Huffman's code for the given message ensemble as:

$$[X] = [X_1, X_2, X_3, X_4, X_5, X_6]$$

$$P[X] = [0.3, 0.25, 0.2, 0.12, 0.08, 0.05]$$

Determine entropy of the source, average length of coded message and the coding Efficiency.

- b) Write a note on:
- i) Binary Erasure channel
  - ii) Average Information.
- c) i) Prove that  $I(X, Y) = H(X) + H(Y) - H(X, Y)$
- ii) What is entropy coding? Derive an expression for coding efficiency.

**SECTION - II**

Q4) Attempt any Three of the following: [18]

- a) With a help of neat schematic, explain the operation of cyclic encoder & syndrome calculator for  $(n, k)$  cyclic code.
- b) Determine the minimal polynomial of  $GF(8)$  whose transfield is  $GF(2)$  with primitive polynomial  $f(x) = X^3 + X^2 + 1$
- c) Explain the following terms related to convolutional code.
  - i) Code tree
  - ii) State diagram
  - iii) code trellis
- d) Determine the generator & parity check matrix for  $(7, 4)$  systematic cyclic code using suitable primitive polynomial.

Q5) Attempt any Two of the following: [16]

- a) A convolutional encoder using three shift registers and  $r=1/2$  has two generating vectors as:  $g_1 = [1 \ 1 \ 1]$  and  $g_2 = [011]$
- i) Sketch the encoder configuration
  - ii) Determine the generator matrix
  - iii) If the message sequence is (1011), determine the output sequence of the encoder.
  - iv) Draw code tree and state diagram.

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- b) Design a (7,3) RS double error correcting code for message  $(\alpha, \alpha^2, \alpha^6)$  & determine the code polynomial & code using nonsystematic & Systematic method.
- c)
  - i) Explain the distance properties of convolutional code.
  - ii) Explain the procedure for generation of systematic cyclic code.

**Q6) Attempt any two of the following:**

**[16]**

- a) Design an encoder and syndrome calculator for the (7,4) Cyclic code generated by,  $g(X)=x^3+x+1$  and verify its operation using the message vector(1101). Also determine syndrome vector for error pattern (0001000).
- b) A(15,7) BCH double error correcting code has the generator polynomial,  $g(x)=x^8+x^7+x^6+x^4+1$ . Find the transmitted code word if the received code word is  $X^3+X^2$ . Consider primitive polynomial is  $X^4+X+1$ .
- c) Write a note on:
  - i) Cyclic redundancy check code
  - ii) Primitive element



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**B.E.(Electronics) (Part - IV) (Semester - VII) (Revised) (New)**  
**Examination, November - 2016**  
**EMBEDDED SYSTEM DESIGN**  
**Sub. Code : 67527**

Day and Date :Thursday, 17-11-2016  
Time : 2.30 p.m. to 5.30 p.m.

Total Marks : 100

- Instructions :
- 1) All questions are compulsory.
  - 2) Figures to right indicate full marks.
  - 3) Write answers to bits in questions at one place and in sequence. Do not place answers randomly.
  - 4) Answers to the bits written randomly may not be assessed.
  - 5) Write answers neatly and should be legible.
  - 6) Draw diagrams neatly and giving appropriate labels and legends.

**SECTION - I**

**Q1) Solve any three: (6 marks for each question) [18]**

- a) Classify embedded system in to three categories and state important features of each class.
- b) Explain the need of watchdog timer and reset after watched time.
- c) What will be the result, after execution of following instructions:
  - i) ADDEQ R2, R4, R5;
  - ii) MOVS PC, R14;
  - iii) LDR R1, [R2, #16];
  - iv) LDRH r11, [r0];
  - v) STMFD R13, {R0-R14}^;
  - vi) SWP R0, R1, [R2];
- d) Explain with suitable example and diagram pre and post indexing addressing mode.

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**Q2) Solve any two: (8 marks for each question)**

**[16]**

- a) Draw CPSR, explain purpose of each Mode of ARM processor.
- b) Explain encoding of SWI instruction. Discuss application of SWI instruction to call a function in supervisory mode with suitable arguments.
- c) Why it is necessary to define separate stack area for each mode, write program to set stack pointer for IRQ mode, Assume ARM is in supervisor mode.

**Q3) Solve any two: (8 marks for each question)**

**[16]**

- a) How Start, Stop, Repeat start and Acknowledge conditions are created in I2C Bus.
- b) With suitable timing diagram discuss CAN bus arbitration process.
- c) With suitable diagram explain why SPI is data exchange protocol?

### **SECTION - II**

**Q4) Answer any three of the following:**

**[18]**

- a) Explain the role of various buffers in Memory Acceleration Module (MAM) and operation modes of MAM.
- b) Describe with diagram the oscillator selection algorithm for LPC 2148.
- c) What are various reset options available on LPC 2148?
- d) How power optimization can be achieved using Power Control block and what are the registers associated with power control?



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**Q5)** Answer any two of the following

**[16]**

- a) Explain with registers associated with the Pin Connect Block of LPC 2148.
- b) Differentiate between Fast GPIO and Legacy GPIO on LPC 2148. Explain role of FIOMASK register.
- c) Differentiate between UART0 and UART1 on LPC 2148 microcontroller chip.
- d) Explain the role of Boot loader on LPC 2148.

**Q6)** Answer any two of the following:

**[16]**

- a) State different states of tasks and explain.
- b) What is the role of semaphores in resolving shared resources problem?
- c) Explain priority inversion problem associated with memory management on RTOS.



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**B.E. (Electronics) (Part - I) (Semester - VII) (Revised) (New)**  
**Examination, November - 2016**  
**COMPUTER NETWORK**  
**Sub. Code : 67528**

Day and Date : Monday, 21 - 11 - 2016

Total Marks : 100

Time : 2.30 p.m. to 5.30 p.m.

- Instructions :
- 1) All questions are compulsory.
  - 2) Figures to the right indicate full marks.
  - 3) Assume necessary data wherever required.

**SECTION - I**

**Q1) Solve any two: [16]**

- a) What is network topology? Draw various topologies & compare them.
- b) With respect to HDLC explain following terms:
  - i) I-Frame
  - ii) S-Frame
- c) With a neat schematic explain working principle of Routing Information Protocol.

**Q2) Solve any two: [16]**

- a) Draw OSI model & explain in brief the functions at each layer.
- b) How sliding window protocol works for flow control in DLL? Explain with neat schematic.
- c) What is traffic shaping? Explain Leaky bucket algorithm.

**Q3) Solve any three: [18]**

- a) A company is granted the site address 201.70.64.0. The company needs six subnets. Design the subnets.
- b) Write short notes on types of station and modes of operations of HDLC.
- c) Explain with neat schematic source routing bridge.
- d) Compare IPV4 and IPV6.

**P.T.O.**

**SECTION - II**

**Q4) Solve any two of the following: [18]**

- a) What are the contents of UDP header? Explain each in detail.
- b) Draw and explain various TCP services.
- c) Explain how flow control is achieved in transport layer.

**Q5) Solve any two of the following: [16]**

- a) Draw and explain TELNET protocol.
- b) With suitable example explain HTTP protocol.
- c) With suitable example explain FTP protocol.

**Q6) Solve any two of the following: [16]**

- a) State and explain public key algorithm.
- b) What are security attacks? Explain each in detail.
- c) State and explain application of message integrity and authentication.



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**B.E.(Electronics) (Semester-VII) (Revised)**  
**Examination, November - 2016**  
**IMAGE PROCESSING**  
**Sub. Code : 67529**

Day and Date : Wednesday, 23 - 11 - 2016

Total Marks : 100

Time : 2.30 p.m. to 5.30 p.m.

- Instructions :
- 1) All questions are compulsory.
  - 2) Figure to right indicate full marks.

**Q1) Attempt any Four: [20]**

- a) Explain image acquisition using single sensor.
- b) Explain different types of distances used in image processing.
- c) Explain sampling and quantization process for images.
- d) Explain power law transformation used in image processing.
- e) Explain image acquisition using sensor strip.

**Q2) Attempt any Two: [16]**

- a) Explain different fundamental steps in digital image processing.
- b) Describe various application of image processing.
- c) Explain concept of image formation model.

**Q3) Attempt any Two: [14]**

- a) Explain Intensity level slicing and Bit plane slicing used in image processing.
- b) What is Histogram matching? Explain procedure for obtaining histogram matching.
- c) Explain various logical operations used for image enhancement

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**Q4) Attempt any Four:**

**[20]**

- a) What do you mean by sharpening of image? How it is done?
- b) Explain order statistic filters.
- c) What is segmentation? Describe steps to do it.
- d) Explain smoothing linear filters.
- e) Describe edge models.

**Q5) Attempt any Two:**

**[16]**

- a) Explain region splitting and merging.
- b) Describe edge detection and various mask used for that.
- c) Describe Thresholding and Write an algorithm used for global Thresholding.

**Q6) Attempt any Two:**

**[14]**

- a) Explain HSI color model.
- b) Explain pseudo color image processing.
- c) Explain converting colors from HSI to RGB Model and vice versa.

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**B.E. (Electronics Engineering) (Semester - VIII) (Pre revised)**  
**Examination, November - 2016**

**BIOMEDICAL CONTROL & INSTRUMENTATION**

**(Elective - II)**

**Sub. Code : 49439**

**Day and Date : Thursday, 10-11-2016**

**Total Marks : 100**

**Time : 2.30 p.m. to 5.30 p.m.**

- Instructions :**
- 1) All questions are compulsory.
  - 2) Use suitable assumptions if required.
  - 3) Draw necessary figures on right side of answer sheet.

**SECTION - I**

**Q1) Solve any THREE: [18]**

- a) Explain cardiovascular system and Cardiac Cycle.
- b) Draw diagram illustrating the working of Cardiac Pacemakers.
- c) Name the different types of electrodes used for a Bio-medical Instrumentation system.
- d) Explain in brief Measurement of Blood pressure.

**Q2) Solve any TWO: [16]**

- a) What is called Respiratory rate? How it can be measured?
- b) What is Regulation of Breathing? How oxygen contents of blood are measured?
- c) What is the frequency range of biomedical signals? Explain the requirements of recorder used for these signals.

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**[16]**

**Q3) Solve any TWO:**

- a) With neat sketch explain electrodes used for ECG.
- b) Explain computerized patient monitoring system.
- c) With neat sketch explain measurement of continuous Cardiac Output.

**SECTION - II**

**Q4) Attempt any THREE from following:**

**[18]**

- a) With neat labeled diagram, explain the structure of neuron in nervous system.
- b) Explain mechanism of hearing with the help of human ear anatomy.
- c) What is meant by evoked response? Explain with example.
- d) What are different lung volumes associated with pulmonary measurement.

**Q5) Attempt any TWO:**

**[16]**

- a) With neat sketch explain different components of human nervous system (CNS, PNS & ANS).
- b) With neat sketch explain the functioning of motor unit in muscle fiber. Explain the characteristics of biopotential generated by muscle fiber.
- c) Explain in detail the methods used for pulmonary flow measurements.

**Q6) Attempt any TWO:**

**[16]**

- a) What are different types of hearing losses? Explain working of pure tone audiometer.
- b) With neat sketch explain the anatomy of human eye.
- c) Explain the role of kidney for the regulation of water and electrolyte balance. What is peritoneal dialysis?

